21000 Series Size 8 Double Stack Hybrid Linear Actuators

Size 8 Double Stack Hybrid Stepper Motor Linear Actuators provide enhanced performance over a single stack.

Improved Performance & New Linear Motion Design Opportunities in a 20 mm Frame Size

3 Available Designs

- Captive
- Non-Captive
- External Linear

The 21000 Series is available in a wide variety of resolutions - from 0.000098 in (.0025 mm) per step to 0.00157 in (0.04 mm) per step. The Size 8 actuator delivers thrust of up to 17 lbs. (75 N).

Assembly options include: Incremental encoders, proximity sensors (captive types only), anti-backlash and custom nuts, and TFE coated lead screws.



Specifications

Size 8 Double Stack: 21 mm (0.8-in) Hybrid Linear Actuator (1.8° Step Angle)					
	Captive	21M4 t			
Part No.	Non-Captive	tive 21L4			
	External Linear	E21M4 t			
Wiring	Bipolar				
Winding Voltage	2.5 VDC 5VDC 7.5 VDC				
Gurren! (RMS)/phase	1.32A	.65A	.43A		
Resistance/phase	1.9 !1 7.7 !1 17.		17.3 !1		
Inductance/phase	0.8 mH 3.2 mH 6.1 mH				
Power Consumption	6.5 WTotal				
Rotor Inertia	2.6 gern'				
Insulation Class	Class B (Class F available)				
Weight	2.4 oz (43 g)				
Insulation Resistance	20 M!1				

tPart numtJering information.oo page 84.

Linear Travel / Step		
in (3.56mm)	Order Code I.D.	
inches mm		
.0025	AA	
.0030•	N	
.005	AB	
.DOW	К	
0.01	AC	
.0121·	J	
.02	AD	
.04	Pf	
.04	Pf	
	in (3.56mm) mm .0025 .0030 .005 .DOW .001 .0121 .02 .04	

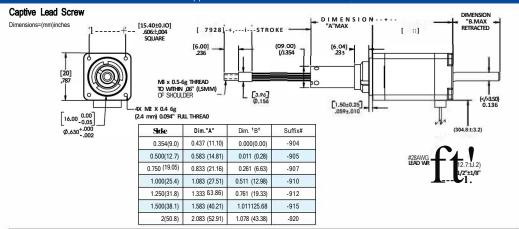
 --Valuestruncated
 Standard motors are Class B rated for maximum temperature of 130° C.

Special drive considerations may be necessary when leaving sllaft fully extended or fully retracted.





• 21000 Series • Size 8 Double Stack Stepper Motor Linear Actuator



Non-Captive Lead Screw

Dimensions=(mm)inches

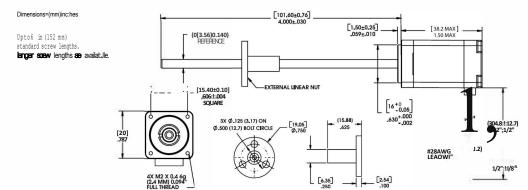
Upto6 in (152 mm)

standard screw lengths.

langer soew lengths are available.

[101.60±0.76] [15.40±0.10]_, .606:!:.004 SQUARE 4,000±,030 [1.50±0.25] [38.2 MAX] 1.50 MAX [3.0] [20] .767 (0[3.56]0.140) REFERENCE 4XM2X0.46g 16⁺⁰ -0.05 .630^{+.000} -.002 (304.8:!:12.7) M2X0.46g (2.4 MM) 0.094 FULL THREAD TO WITHIN (.75) 12": 1/2" #28AWG (12.7:1:3.2)

External Linear



.AM !!E K "

1/2:!:1/8"

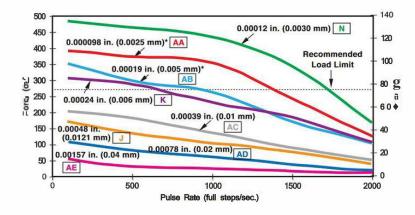
• 21000 Series • Size 8 Double Stack Stepper Motor Linear Actuator

FORCE vs. PULSE RATE

- Chopper - 0 .14 (3.56) Lead Screw

- Bipolar - 8:1 Motor Coil to Drive Supply Voltage

- 100% Duty Cycle



FORCE vs. LINEAR VELOCITY

- Chopper - 0 .14 (3.56) Lead Screw

-Bipolar - 8:1 Motor Coil to Drive Supply Voltage

- 100% Duty Cycle 500 - r - - - - - 1 4 0 0.00012 in. (0.0030 mm)[[] 450 120 0.000098 In. (0.0025 m m) * • 400 Recommended 0.00019 In. (0.005 mm) • • 100 350 Load Limit J 300 250 0.00024 in. (0.006 mm) KJ 60 0 ♦ 200 0-00039 in. (0-01 mm) • 150 40 0.00048 in. (0.0121 mm) IJJ 100 0.00078 In. (0.02 mm) • 20 50 0.00157 in. (0.04 m m) • 1.5 [38.1] 0.5(12.7) 1.0 [25.41 2.0 [50.8] 2.5 (63.51 3.0 [76.2] 0 Linear Velocity (inJsec. [mm/sec.])

*Gare shoold be taken when utilizing these screw pitches to ensure that theph}'l.licalloadlimitl.lofthemotorarenotexceeded.Pleaseconsult thefactoryforadvice in selecting the proper pitch foryourapplication.

Rampingcanincreasethepetiormanceofamotoreitherbyincreasing tf7e topspeed orgetting a heavier load accelerated upto speed faster. Also, decelerationcan be used to stop tf7ernotor without overshoot.

NOTE: All chopper dlive curves were created with a 5 voll motor and a 40voltnowers upply.

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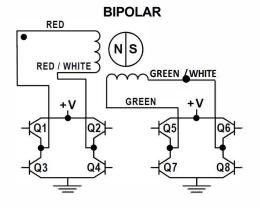
WithI./Rdrivespeakforceandspeedsarereduced,usingaunipolar drivewillvieldafurther30%force reduction.

Identifying the Hybrid Part Number Codes when Ordering

identifying the hybrid Part Number Codes when Ordering						
E	21	M	4	N	2.5	210
Prefix (include only when using the following) A=ACoil Sea/C Synchrocous Datastisety) E = External K = External with 40 thread form P = Proximity Sensor	Series Number Designation 21 = 21000 (Series numbers represent approximate width of motor body)	style L= 1.8° Non-captive M = 1.8°Captive or External (use "E"or"K" Prefix for External version)	Coils 4 = Bipolar (4wire)	Code 10 Resolution TraveVStep AA'= .000098-in (.0025) N = .00012-in (.0030) AB = .00019-in (.005) K = .00024-in (.006) AC = .00039-in (.01) J = .00048-in (.0121) AD = .00078-in (.02) AE = .00157-in (.04) TFEnotavailable	Voltage 2.5 = 2.5 VDC 05=5VDC 7.5 = 7.5 VDC CustomVavailable	Suffix strake Example:-910 = 1-in (RefentoStroked?artonCaptive motorseriesproducpage) Suffix also represents: -800 = Metric -900 = External Linear with grease and flanged nut -XXX = Proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

NOTE: Dashes must be included if Part Number (-) as shown above. For assistance can our Erigineering Team at 203 756 7441.

Hybrids: Wiring



Hybrids: Stepping Sequence

	Bipolar	Q2-Q3	Q1-Q4	Q6-Q7	Q5-Q8	
2	Step					A
EXTEND CW	1	OΝ	OFF	OΝ	OFF	Ш
Ε	2	OFF	ON	ΟN	OFF	CCW
	3	OFF	ON	OFF	ON	RETRACT
•	4	ΟN	OFF	OFF	ON	툪
	1	ON	OFF	ON	OFF	

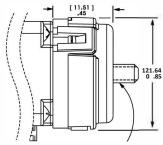
Note: Half stepping is accomplished by inserting an off state between transitioning phases.

Encoders Designed for All Sizes of Hybrid Linear Actuators

All Haydon Hybrid Linear Actuators are available with specifically designed encoders for applications that require feedback. The compact optical incremental encoder design is available with two channel guadrature TTL squarewave outputs. An optional index is also available as a 3rd channel. The Size 8 Encoder provides resolutions for applications that require 250 and 300 counts per revolution. Encoders are available for all motor configurations - captive, non-captive and ex1emal linear.

Simplicity and low cost make Encoders ideal for both high and low volume motion control applications. The internal monolithic electronic module converts the real-time shaft angle, speed, and direction into TTL compatible outputs. The encoder module incorporates a lensed LED light source and monolithic photodetector array with signal shaping electronics to produce the two channel bounceless TTL outputs.

21 mm 21000 Series Size B



NOTE: Lead Screw extends beyond encoder an specific captive and non-captive motors. External linear shaft extension is available upon request.

Single Ended Encoder - Pinout - Size 8			
Connector Pin #	Description		
1	+5VDC Power		
2	Channel A		
3	Ground		
4	Channel B		



Size8with Encoder

Electrical Specifications					
	Minimum	Typical	Maximum	Units	
Input Voltage	4.5	5.0	5.5	VDC	
Output Signals	4.5	5.0	5.5	VDC	

2channelQUadraturemsquarewaveoutputs.

Channel Bleads A for a dockwise rotation of the rotor viewed from the encoder cover.

Tracks at speeds of 0 to 100,000 cycles/sec.

Optional indexavailableasa3rdchannel(ooepulseperrevolutioo).

Operating Temperature		
Size 8	Minimum	Maximum
	-10°C(W F)	85°C (185°F)

Mechanical Specifications	
1	Maximum
Acceleration 1	250,000 rad/sec2
Vibration (5 Hz to 2 kHz) 1	20 g

Resolution				
4 Standard Cycles Per Revolution (CPR) or Pulses Per Revolution (PPR)				
Size 8	CPR	250	300	
Size 8	PPR	1000	1200	

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