

21000 Series Size 8 Hybrid Linear Actuators

Size 8 Hybrid Precision Stepper Motor is part of our extensive, award winning miniature motor product line and is one of the world's smallest linear actuators.

More Compact Option for Motion Applications

The 21000 Series Size 8 Linear Actuator occupies a minimal 0.8" (21 mm) space and includes numerous patented innovations that provide customers high performance and endurance in a very small package.

3 Available Designs

- Captive
- Non-Captive
- External Linear

The 21000 Series is available in a wide variety of resolutions - from 0.00006" (.0015mm) per step to 0.00157" (0.0 mm) per step.

The Size 8 Actuator delivers thrust of up to 10 lbs (44 $\mbox{N}).$



External Linear

Specifications

Size 8: 21 mm (0.8-in) Hybrid Linear Actuator (1.8° Step Angle)				
	Captive	21H4 – – – [†]		
Part No.	Non-Captive 21F4 –		- †	
	External Linear	E21H4 –	- †	
Wiring		Bipolar		
Winding Voltage	2.5 VDC 5 VDC 7.5 VDC			
Current (RMS)/phase	.49 A .24 A .16 A			
Resistance/phase	5.1 Ω 20.4 Ω 45.9 Ω			
Inductance/phase	1.5 mH 5.0 mH 11.7 mH			
Power Consumption	2.45 W Total			
Rotor Inertia	1.4 gcm ²			
Insulation Class	Class B (Class F available)			
Weight	1.5 oz (43 g)			
Insulation Resistance	20 MΩ			

Linear Travel / Step Order Screw Ø.14-in (3.56mm) Code I.D. inches mm []** .00006 .0015* AA** .000098* .0025 .00012 .0030* Ν .005 AB .00019* .00024 .006* Κ .00039* AC .01 .00048 .0121* J .02 .00078* AD .00157 .04 AE

*Values truncated

**TFE coating not available

Standard motors are Class B rated for maximum temperature of 130°C.

[†]Part numbering information on page 4

Special drive considerations may be necessary when leaving shaft fully extended or fully retracted.



21000 Series • Size 8 Single Stack Stepper Motor Linear Actuators



Non-Captive Lead Screw



External Linear



21000 Series • Size 8 Single Stack Stepper Motor Linear Actuators

FORCE vs. PULSE RATE

- Chopper
- Bipolar
- 100% Duty Cycle
- Ø .14 (3.56) Lead Screw

Force (oz.)	400	0.00006 in. (0.0015 mm)* 0.00006 in. (0.0015 mm)* 0.00012 in. (0.0030 mm) N Recommended 0.00024 in. (0.006 mm) K 0.00024 in. (0.006 mm) K 0.00048 in. (0.0121 mm) d 10	Force (N)
	0+0	200 400 600 800 1000 1200 1400 1600 1800 2000 2200 2400 Pulse Rate (full steps/sec.)	
		0.00019 in. (0.005 mm)*	ce (N)
		0.00039 in. (0.01 mm) AC 0.00078 in. (0.02 mm) AD	Ford
		0.00157 in. (0.04 mm)	

FORCE vs. LINEAR VELOCITY

- Chopper
- Bipolar
- 100% Duty Cycle
- Ø .14 (3.56) Lead Screw

*Care should be taken when utilizing these screw pitches to ensure that the physical load limits of the motor are not exceeded. Please consult the factory for advice in selecting the proper pitch for your application.

NOTE: All chopper drive curves were created with a 5 volt motor and a 40 volt power supply.

Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot.

With L/R drives peak force and speeds are reduced, using a unipolar drive will yield a further 30% force reduction.

	0.00039 in. (0.01 mm)
	0.00046 m. (0.012 mm) (m. (0.02 mm) (m. (0.0
	0.00157 in. (0.04 mm)
	Linear Velocity (in./sec. [mm/sec.])
	0.00006 in. (0.0015 mm)*
	0.00006 in. (0.0015 mm)* U 0.000098 in. (0.0025 mm)* AA
e)	0.00006 in. (0.0015 mm)* U 0.000098 in. (0.0025 mm)* AA 0.00012 in. (0.0030 mm) N
106 (077)	0.00006 in. (0.0015 mm)* U 0.000098 in. (0.0025 mm)* AA 0.00012 in. (0.0030 mm) N 0.00019 in. (0.005 mm)* AB
1000 (07-)	0.00006 in. (0.0015 mm)* U 0.000098 in. (0.0025 mm)* AA 0.00012 in. (0.0030 mm) N 0.00019 in. (0.005 mm)* M 0.00024 in. (0.006 mm)
100G (07.)	0.00006 in. (0.0015 mm)* U 0.000098 in. (0.0025 mm)* AA 0.00012 in. (0.0030 mm) N 0.00019 in. (0.005 mm)* Af 0.00024 in. (0.006 mm) K
	0.00006 in. (0.0015 mm)* U 0.000098 in. (0.0025 mm)* AA 0.00012 in. (0.0030 mm) N 0.00019 in. (0.005 mm)* AF 0.00024 in. (0.006 mm) K
	0.00006 in. (0.0015 mm)* U 0.000098 in. (0.0025 mm)* AA 0.00012 in. (0.0030 mm) N 0.00019 in. (0.005 mm)* N 0.00024 in. (0.006 mm) K



ADVANCED MOTION SOLUTIONS

Identifying the Hybrid Part Number Codes when Ordering						
E	21	Н	4	AB	7.5	910
Prefix(include only when using the following) $E = External$ $K = External with40^{\circ} threadformP = ProximitySensorS = Home PositionSwitch$	Series Number Designation 21 = 21000 (Series numbers represent approximate width of motor body)	Style F = 1.8° Non-captive H = 1.8°Captive or External (use "E" or "K" Prefix for External version)	Coils 4 = Bipolar (4 wire)	$\begin{tabular}{lllllllllllllllllllllllllllllllllll$	Voltage 2.5 = 2.5 VDC 05 = 5 VDC 7.5 = 7.5 VDC Custom V available	Suffix Stroke Example: -910 = 1-in (Refer to Stroke chart on Captive motor series product page.) Suffix also represents: -800 = Metric -900 = External Linear with grease and flanged nut -XXX = Proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

NOTE: Dashes must be included in Part Number (-) as shown above. For assistance call our Engineering Team at 203 756 7441.

Hybrids: Wiring



Hybrids: Stepping Sequence

	Bipolar	Q2-Q3	Q1-Q4	Q6-Q7	Q5-Q8	
EXT	Step					
B	1	ON	OFF	ON	OFF	<
CW	2	OFF	ON	ON	OFF	SO
	3	OFF	ON	OFF	ON	ACT
¥.	4	ON	OFF	OFF	ON	ETR
	1	ON	OFF	ON	OFF	

Note: Half stepping is accomplished by inserting an off state between transitioning phases.

Encoders Designed for All Sizes of Hybrid Linear Actuators

All Haydon Hybrid Linear Actuators are available with specifically designed encoders for applications that require feedback. The compact optical incremental encoder design is available with two channel quadrature TTL squarewave outputs. An optional index is also available as a 3rd channel. The Size 8 Encoder provides resolutions for applications that require 250 and 300 counts per revolution. Encoders are available for all motor configurations – captive, non-captive and external linear.

Simplicity and low cost make Encoders ideal for both high and low volume motion control applications. The internal monolithic electronic module converts the real-time shaft angle, speed, and direction into TTL compatible outputs. The encoder module incorporates a lensed LED light source and monolithic photodetector array with signal shaping electronics to produce the two channel bounceless TTL outputs.

21mm 21000 Series Size 8



NOTE: Lead Screw extends beyond encoder on specific captive and non-captive motors. External linear shaft extension is available upon request.

Single Ended Encoder - Pinout - Size 8				
Connector Pin #	Description			
1	+5 VDC Power			
2	Channel A			
3	Ground			
4	Channel B			



Electrical Specifications					
	Minimum	Typical	Maximum	Units	
Input Voltage	4.5	5.0	5.5	VDC	
Output Signals	4.5	5.0	5.5	VDC	

2 channel quadrature TTL squarewave outputs.

Channel B leads A for a clockwise rotation of the rotor viewed from the encoder cover.

Tracks at speeds of 0 to 100,000 cycles/sec.

Optional index available as a 3rd channel (one pulse per revolution).

Operating Temperature		
Sizo 9	Minimum	Maximum
3120 0	- 10°C (14°F)	85°C (185°F)

Mechanical Specifications				
	Maximum			
Acceleration	250,000 rad/sec2			
Vibration (5 Hz to 2 kHz)	20 g			

Resolution				
4 Standard Cycles Per Revolution (CPR) or Pulses Per Revolution (PPR)				
CPR 250 300				
SIZE 8 PPR		1000	1200	





Encoder Ready Option Shown 34000 Series Size 17



Extended Rotor Journal Shown 34000 Series Size 17







Integrated Anti-Backlash Nut

Encoder Ready Option for all Hybrid Sizes

Our Hybrid Linear Actuators can now be manufactured as an Encoder Ready Actuator. Encoder Ready Actuators can be used to install several popular hollow shaft encoders. Available with an extended rotor journal and a threaded rear housing. The motor uses a proprietary manufacturing process which incorporates engineering thermoplastics in the rotor drive nut and a stainless steel Acme Lead Screw that allows the motor to be much more efficient and durable than today's more commonly used V-thread bronze nut configurations.

Extended Rotor Journal for all Hybrid Sizes

Available with an extended rotor journal. The extended rotor journal can be used for encoder installation, manual adjustment, or flag installation for a positioning sensor.

Home Position Switch for Hybrids

A miniature electronic Home Position Switch capable of monitoring the home positions of linear actuators. The switch mounts on the rear sleeve of captive linear motors and allows the user to identify start, stop or home positions.

When ordering motors with the home position switch the part number should be preceded by an "S" prefix.

End of Stroke Proximity Sensor for all Hybrid Sized

The Sensor incorporates a hall effect device, which is activated by a rare earth magnet embedded in the end of the internal screw. The compact profile of the sensor allows for installation in limited space applications. The sensor has a virtually unlimited cycle life. Special cabling and connectors can also be provided.

When ordering motors with the proximity sensor, the part number should be preceded by a "P" prefix.

Black Ice® and Kerkote® TFE Coated Lead Screws*

TFE Coated Lead Screws for applications that require a *greaseless* screw and nut interface.

A *dry* (non-lubricated) TFE coated lead screw provides improved performance in both life and thrust as compared to a conventional stainless steel lead-screw. TFE can be applied to a wide variety of lead-screw pitches and is available for our brand captive, non-captive and external linear actuators. Not available for 0.00006-in (.0015 mm) and 0.000098-in (.0025 mm) resolutions.

*Certain conditions apply.

Integrated Anti-Backlash Nut for Hybrids*

Most sizes (except Size 34) of our captive and non-captive hybrid stepper motors can be equipped with an integral anti-backlash feature. There is a normal backlash between the lead screw and integral rotor nut.

Our actuators are designed for millions of cycles. However over time, additional backlash could increase and eventually double. Haydon Kerk Integrated Anti-Backlash Nut can eliminate all backlash. Designed specifically for our captive and non-captive hybrid motors, nuts use an opposing spring force to eliminate backlash between the screw and the nut interface. The nuts will self-compensate and accommodate any wear. Haydon Kerk Motion Solutions application engineers can help you select the appropriate preload for your application

*Except Size 34.

